To Predict > To Design > To Perform

ME, ECE, IE Capstone Design Programs

Team #28: Moonwalker Robotic Skates Evan Guinta (ME), Jesse Kliebert (ME), Matthew Ohrberg (EE)

Background

Last Mile Problem

- After commuting by car, bus, train, etc., most people still have to travel a little further to get to there final
- destination.
- For that last part of the journey, will the commuter walk, bike, or skateboard?

Objective Statement

- Design and prototype a solution for the last mile problem.
- This design will have two wheeled platforms that can be easily worn over ones shoes.
- This design will have an electromechanical system that • will propel the user forward.

Competitors

RocketSkates

Boosted Board



www.google.com, keyword: RocketSkates





www.google.com, keyword: Boosted Board

Specifications

Test	Specs	Results
Weight Test	<8 lbs	8.75 lbs
Load Test	250 lbs	250 lbs
Speed Test	10 mph	6 mph
Mile Range	2 miles	2.1 miles

Sponsors: Brian LeBlanc











Project Timeline

Aug	Sept	Oct	Nov	Dec) Jan	Feb	Mar	Apr	May
 Project Specifications 	•Concept Generation	•Engineering Analysis	•Manufacturing and Testing Plan	•Fall Presentation	•Began Manufacturin	g	•Completed Manufacturing	•Testing	•Project Completion



College of Engineering Department of Mechanical & Industrial Engineering



PWM (Both Skates)



- The pulse width modulation activates for both skates when the IR sensor and Tachometer are activated.
- The PWM controls the speed of the motors.

Testing

Bluetooth Linked



- Both Bluetooth modules where programmed using AT commands through both Arduino 101s.
- Once the modules are paired and linked the blue and green LEDs turn on





- Total distance: 2.1 miles
- Max speed:
- 8mph
- Avg. speed: 4mph

Safety Equipment



Shop Safety

- Safety Glasses
- No Loose Clothing
- Long Pants
- Thermal Gloves when Plastic Welding
 - Testing Safety
- Helmet (Complies with ASTM) F1492-08 Standard)
- Elbow Pads
- Knee Pads
- Wrist Pads

Conclusion

- The skates were able to withstand the maximum 250 lb weight limit
- Each individual skate was approximately 0.7 lbs over the weight limit.
- The motor was successfully controlled by the different sensors.
- The mile range was achieved at a riding speed of 7mph.
- Improvements can be made for comfort and durability.

Adviser: Dr. Wanjun Wang

