To Predict > To Design > To Perform

ME, ECE, IE Capstone Design Programs

Champions of the First Bengal Bot Brawl

Objective:

Design and build a robot to compete in the Robot Battles competition

- Electrically powered and safely controlled
- Weight Class: 12-30 lbs (±2.5%)
- 16 ft x 16 ft combat area
- Victory Conditions:
 - Ring out Push opponent out of combat area
 - Disable/destroy opponent

Design Goals:

<u>Highly Mobile</u>

Durable Powerful Efficient Safe

Testing and Validation:

- Drive: Speed and torque tests
- Weapon: Weight lifting capacity
- Frame and Armor: Impact testing
- Electronics : Current-voltage tests, signal analysis, control test model

Manufacturing:

- Ordered stock material and off-the-shelf components
- Hand machined parts to specification in the AMMF

Safety:

- Operational safety
- Kill switch functionality on robot included
- Delicate components housed appropriately
- Proper use of manufacturing and testing equipment



Sponsors: David Bourg / Dimitris E. Nikitopoulos







Project #17: Combat Robot #1 – "Goliath" Joseph Ammond, Calvin Durel, Paul Florida, Dalton Guidry, Luke Osborn

Weapon (Flipper):

- Motor provides 188lb-ft. of torque to weapon via miter gears
- Weapon arm used to upend opponents of up to 30lb and self-right
- Materials:
 - Al 6061-T6
 - Al 7075-T6
 - Steel Miter Gears
 - Banebots RS-550
 - Turnigy 5000mAh 3s 30C LiPo pack

Drivetrain (DT):

- Omnidirectional propulsion at speeds up to 10ft/s
- Materials:
 - 4" steel mecanum wheels
 - Andymark 9015 DC **Brushless Motor**
 - Turnigy 5000mAh 3s 30C



College of Engineering Department of Mechanical & Industrial Engineering





		Design Specifications	Tested Specificati
	Weight	30 lbs	30.55 lb
	Dimensions	24"x17"x5"	26″x17″x
	Maximum Speed	7 ft/s	10 ft/s
	Lifting Capability	30 lbs	30 lbs
	Battery Life	40 min	40 min
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Final lesting (Apr. 2017-May. 2017)

National Competition (May. 2017)

Advisers: A.J. McPhate



